sgi

Message Passing Toolkit (MPT) User's Guide

007-3773-009

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New Features in This Manual

This update to the *Message Passing Toolkit (MPT) User's Guide* supports the MPT 1.21 release.

Major Documentation Changes

Added the following:

- A new chapter for system administrators in Chapter 2, "Administrating MPT" on page 5.
- Information about the ${\tt MPI_STATS_FILE}$ variable in "MPI Internal Statistics" on page 33.
- Revised variable description in "MPI_CTRL_RING" on page 49.
- mpi_alltoallw to the list in "MPI Supported Profiled Functions".

Record of Revision

Version	Description
001	March 2004 Original Printing. This manual documents the Message Passing Toolkit implementation of the Message Passing Interface (MPI).
002	November 2004 Supports the MPT 1.11 release.
003	June 2005 Supports the MPT 1.12 release.
004	June 2007 Supports the MPT 1.13 release.
005	October 2007 Supports the MPT 1.17 release.
006	January 2008 Supports the MPT 1.18 release.
007	May 2008 Supports the MPT 1.19 release.
008	July 2008 Supports the MPT 1.20 release.
009	October 2008 Supports the MPT 1.21 release.

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About This Manual

This publication documents the SGI implementation of the Message Passing Interface (MPI).

MPI consists of a library, which contains both normal and profiling entry points, and commands that support the MPI interface. MPI is a component of the SGI Message Passing Toolkit (MPT).

MPT is a software package that supports parallel programming on large systems and clusters of computer systems through a technique known as *message passing*. Systems running MPI applications must also be running Array Services software version 3.1 or later. For more information on Array Services, see Chapter 3, "Array Services" in the *Linux Resource Administration Guide*.

Related Publications and Other Sources

Material about MPI is available from a variety of sources. Some of these, particularly webpages, include pointers to other resources. Following is a grouped list of these sources.

The MPI standard:

- As a technical report: University of Tennessee report (reference [24] from Using *MPI: Portable Parallel Programming with the Message-Passing Interface*, by Gropp, Lusk, and Skjellum).
- As online PostScript or hypertext on the Web:

http://www.mpi-forum.org/

• As a journal article in the *International Journal of Supercomputer Applications*, volume 8, number 3/4, 1994. See also *International Journal of Supercomputer Applications*, volume 12, number 1/4, pages 1 to 299, 1998.

Book: Using MPI: Portable Parallel Programming with the Message-Passing Interface, by Gropp, Lusk, and Skjellum, publication TPD-0011.

Newsgroup: comp.parallel.mpi

SGI manuals: *SpeedShop User's Guide* and *Linux Resource Administration Guide* for information on Array Services

Obtaining Publications

You can obtain SGI documentation in the following ways:

- See the SGI Technical Publications Library at: http://docs.sgi.com. Various formats are available. This library contains the most recent and most comprehensive set of online books, release notes, man pages, and other information.
- You can also view man pages by typing man *title* on a command line.

Conventions

The following conventions are used throughout this document:

Convention	Meaning
command	This fixed-space font denotes literal items such as commands, files, routines, path names, signals, messages, and programming language structures.
manpage(x)	Man page section identifiers appear in parentheses after man page names.
variable	Italic typeface denotes variable entries and words or concepts being defined.
user input	This bold, fixed-space font denotes literal items that the user enters in interactive sessions. (Output is shown in nonbold, fixed-space font.)
[]	Brackets enclose optional portions of a command or directive line.

...

Ellipses indicate that a preceding element can be repeated.

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Introduction

Message Passing Toolkit (MPT) is a software package that supports interprocess data exchange for applications that use concurrent, cooperating processes on a single host or on multiple hosts. Data exchange is done through message passing, which is the use of library calls to request data delivery from one process to another or between groups of processes.

The MPT package contains the following components and the appropriate accompanying documentation:

- Message Passing Interface (MPI). MPI is a standard specification for a message passing interface, allowing portable message passing programs in Fortran and C languages.
- The SHMEM programming model. The SHMEM programming model is a distributed, shared-memory model that consists of a set of SGI-proprietary message-passing library routines. These routines help distributed applications efficiently transfer data between cooperating processes. The model is based on multiple processes having separate address spaces, with the ability for one process to access data in another process' address space without interrupting the other process. The SHMEM programming model is not a standard like MPI, so SHMEM applications developed on other vendors' hardware might or might not work with the SGI SHMEM implementation.

This chapter provides an overview of the MPI software that is included in the toolkit. This overview includes a description of the MPI-2 Standard features that are provided, a description of the basic components of MPI, and a description of the basic features of MPI. Subsequent chapters address the following topics:

- Chapter 3, "Getting Started" on page 13
- Chapter 4, "Programming with SGI MPI" on page 19
- Chapter 5, "Debugging MPI Applications" on page 29
- Chapter 6, "Profiling MPI Applications" on page 31
- Chapter 7, "Run-time Tuning" on page 39
- Chapter 8, "MPI Performance Profiling" on page 51
- Chapter 9, "Troubleshooting and Frequently Asked Questions" on page 59

MPI Overview

MPI was created by the Message Passing Interface Forum (MPIF). MPIF is not sanctioned or supported by any official standards organization. Its goal was to develop a widely used standard for writing message passing programs.

SGI supports implementations of MPI that are released as part of the Message Passing Toolkit. The MPI Standard is documented online at the following address:

http://www.mcs.anl.gov/mpi

MPI-2 Standard Compliance

The SGI MPI implementation is compliant with the 1.0, 1.1, and 1.2 versions of the MPI Standard specification. In addition, the following MPI-2 features (with section numbers from the MPI-2 Standard specification) are provided:

Feature	Section
MPI-2 parallel I/O	9
A subset of MPI-2 one-sided communication routines (put/get model)	6
MPI spawn functionality	5.3
MPI_Alloc_mem/MPI_Free_mem	4.11
Transfer of handles	4.12.4
MPI-2 replacements for deprecated MPI-1 functions	4.14.1
Extended language bindings for C++ and partial Fortran 90 support	10.1, 10.2.4
Generalized requests	4.5.2
New attribute caching functions	8.8

MPI Components

The MPI library is provided as a dynamic shared object (DSO) (a file with a name that ends in .so). The basic components that are necessary for using MPI are the libmpi.so library, the include files, and the mpirun command.

Profiling support is included in the libmpi.so library. Profiling support replaces all MPI_Xxx prototypes and function names with PMPI_Xxx entry points.

MPI Features

The SGI MPI implementation offers a number of significant features that make it the preferred implementation to use on SGI hardware:

- Data transfer optimizations for NUMAlink, including single-copy data transfer
- Use of hardware fetch operations (fetchops), where available, for fast synchronization and lower latency for short messages
- Optimized MPI-2 one-sided commands
- Interoperability with the SHMEM (LIBSMA) programming model
- High performance communication support for partitioned systems via XPMEM

Chapter 2

Administrating MPT

This chapter is provided for system administrators who install, configure, and administrate software on SGI Altix systems. It covers the following topics:

- "Finding the MPT Release Notes" on page 5
- "MPT Installation" on page 5
- "System Configuration" on page 10

Finding the MPT Release Notes

Find the latest MPT release notes on your system, as follows:

```
% rpm -qi sgi-mpt | grep README.relnotes
/usr/share/doc/sgi-mpt-1.21/README.relnotes
```

Next, change directory to the location found, and list the contents of the directory, as follows:

% cd /usr/share/doc/sgi-mpt-1.21
% ls
MPT_UG README.relnotes sgi-mpt.1.21.intel8.template sgi-mpt.1.21.template
The release notes are in a file called README.relnotes.

MPT Installation

This section describes requirements and procedures for MPT installation. After you have installed the MPT and prerequisite software per the instructions in this section, be sure to perform the steps described in "System Configuration" on page 10.

Note: The MPI installation and configuration information found in this chapter is also available in the READ.relnotes file in the /usr/share/doc/sgi-mpt-1.21 directory.

Disk Space Requirements

Disk space requirements for the MPT product are substantially less than 20 Mbytes.

Prerequisites

This section describes software prerequisites for MPT.

SGI ProPack Components

A default install of SGI ProPack is recommended. This provides a number of software components required by MPT. The SGI ProPack RPMs required by MPT include the following:

- sgi-arraysvcs or sgi-sarraysvcs
- sgi-procset
- libbitmask
- libcpuset
- cpuset-utils
- sgi-release
- xpmem

InfiniBand Software Stack

If you are using the InfiniBand interconnect, you must ensure that one of the supported InfiniBand software stacks are installed. These include Voltaire ibhost or Gridstack software packages and the OpenFabrics Enterprise Distribution (OFED) software provided with SGI ProPack 5 SP2 (or later) on SGI Altix XE and SGI Altix ICE systems and SGI ProPack 5 SP3 (or later) on SGI Altix 4000 series systems.

Installing the MPT RPM

MPT is supplied as an RPM file. The name of the file contains the following information:

• Product (sgi-mpt)

- MPT Version (1.21)
- SGI ProPack Version (601)
- Architecture (SGI IA-64 or x86_64 based systems)

For example, if the name of the MPT RPM for the MPT 1.21 release is sgi-mpt-1.21-sgi601r1.ia64.rpm. To install this RPM, log in as root and issue the following command:

rpm -Uvh sgi-mpt-1.21-sgi601r1.ia64.rpm

Installing MPT Software in an Alternate Location

RPM provides a means for creating, installing, and managing relocatable packages. That is, the MPT RPM can be installed in either a default or alternate location.

The default location for installing the MPT RPM is /usr. To install the MPT RPM in an alternate location, use the --prefix option, as shown in the following example. The --prefix option specifies the alternate base directory for the installation of the MPT software (in this case, /tmp).

rpm -i --prefix /tmp sgi-mpt-1.21-sgi601r1.ia64.rpm

Note: If the MPT software is installed in an alternate location, MPT users must set the environment variables PATH and LD_LIBRARY_PATH to specify the search locations for the mpirun command and the run-time libraries, assuming the alternate location of /tmp, as follows:

```
setenv PATH /tmp/bin:${PATH}
export PATH=/tmp/bin:${PATH}
export LD_LIBRARY_PATH=/tmp/lib
export LD_LIBRARY_PATH=/tmp/lib
```

If the site is using environment modules to manage the user environment, then the alternate location should be placed in the mpt modulefile. This approach is the most convenient way to establish environment variable settings that enable MPT program developers and users to access the MPT software when installed in an alternate location. A sample modulefile is located in the /usr/share/doc/sgi-mpt-1.21/ directory. It is suggested that the site install modules in /usr/share/modules/modulefiles.

For more information, see "Using Dynamic Shared Libraries to Run MPI Jobs," later in this chapter.

Using a cpio File for Installation

The cpio file installation method described here is useful when the MPT software is installed in an NFS filesystem shared by a number of hosts. In this case, it is not important or desirable for the RPM database on only one of the machines to track the versions of MPT that are installed. Another advantage of the approach is that you do not need root permission to install the MPT software.

To install MPT using a cpio file, first convert the MPT RPM to a cpio file by executing the rpm2cpio command, as follows:

```
% rpm2cpio sgi-mpt-1.21-1.ia64.rpm > /tmp/sgi-mpt.cpio
```

Once you have created the .cpio file, you are free to install the software beneath any directory in which you have write permission. The following example demonstrates the process.

```
% cd /tmp
% cpio -idmv < sgi-mpt.cpio</pre>
usr/bin/mpirun
usr/include/mpi++.h
usr/include/mpi.h
. . .
usr/lib/libmpi++.so
usr/lib/libmpi.so
usr/lib/libxmpi.so
. . .
% ls -R /tmp/usr
/tmp/usr:
bin include lib local
/tmp/usr/bin:
mpirun
/tmp/usr/include:
MPI.mod mpi.h
                              mpif.h
                  mpi_ext.h
                                                  mpio.h
                                                            mpp
mpi++.h mpi.mod mpi_extf.h mpif_parameters.h mpiof.h
```

```
/tmp/usr/lib:
libmpi++.so* libmpi.so* libsma.so* libxmpi.so*
...
```

If the MPT software is installed in an alternate location, set up an environment module to set environment variables which will be used by compilers, linkers, and runtime loaders to reference the MPT software.

Installation Conflicts with Multiple MPIs

The MPT and LAM MPI RPMs conflict with each other. To install both MPT and LAM MPI on the same system, you can install the MPT RPM in an alternate location as described previously "Installing MPT Software in an Alternate Location" on page 7.

Using Dynamic Shared Libraries to Run MPI Jobs

After you have installed the MPT RPM as default, use the following command to build an MPI-based application that uses the .so files:

For C programs, as follows:

% gcc simple1_mpi.c -lmpi
% mpirun -np 2 a.out

For Fortran programs:

% f77 -I/usr/include simple1_mpi.f -lmpi
% mpirun -np 2 a.out

The default locations for the include and .so files and the mpirun command are referenced automatically.

Assuming that the MPT package has been installed in an alternate location (under the /tmp directory), as described earlier in "Installing MPT Software in an Alternate Location" on page 7, the commands to compile, load, and check are, as follows:

```
% gcc -I /tmp/usr/include simple1_mpi.c -L/tmp/usr/lib -lmpi
% ldd a.out
libmpi.so => /usr/lib/libmpi.so (0x40019000)
libc.so.6 => /lib/libc.so.6 (0x402ac000)
libdl.so.2 => /lib/libdl.so.2 (0x4039a000)
/lib/ld-linux.so.2 => /lib/ld-linux.so.2 (0x4000000)
```

As shown above, compiling with alternate-location libraries does not mean that your program will run with them. Note that libmpi.so is resolved to /usr/lib/libmpi.so, which is the default-location library. If you are going to use

an alternate location for the .so files, it is important to set the LD_LIBRARY_PATH environment variable. If the site is using environment modules, this can be done in the mpt modulefile. Otherwise, the user must set LD_LIBRARY_PATH, as in the following example:

```
% setenv LD_LIBRARY_PATH /tmp/usr/lib
% ldd a.out
libmpi.so => /tmp/usr/lib/libmpi.so (0x40014000)
libc.so.6 => /lib/libc.so.6 (0x402ac000)
libdl.so.2 => /lib/libdl.so.2 (0x4039a000)
/lib/ld-linux.so.2 => /lib/ld-linux.so.2 (0x4000000)
```

This example shows the library being resolved to the correct file.

Running MPI Jobs on a Cluster with MPT Alternate Installation

For MPI jobs to run correctly in a cluster environment in which MPT has been installed in an alternate location, you must copy all of the pertinent pieces of MPT to an NFS-mounted filesystem. This is the only way in which all of the nodes in the cluster can access the software, short of installing the same MPT RPM on each node. The following method is one way to accomplish this (assuming /data/nfs is an NFS-mounted directory and MPT has been installed in the alternate location /tmp/usr):

```
nodel # tar cf /tmp/mpt.1.21.tar /tmp/usr
nodel # cp /tmp/mpt.1.21.tar /data/nfs
nodel # cd /data/nfs
nodel # tar xf mpt.1.21.tar
nodel # setenv LD_LIBRARY_PATH /data/nfs/lib
nodel # /data/nfs/bin/mpirun -v -a <arrayname> host_A,host_B -np 1 a.out
Replace the <arrayname> in the above example with an array services array name that
contains both host_A and host_B.
```

System Configuration

This section describes additional system configuration issues that a system administrator may need to address before running the SGI MPT software.

Starting Prerequisite Services

MPT requires that procset and array services be started and that the XPMEM kernel module be loaded. These tasks are performed automatically by a reboot of the system occurring after the system configuration tasks in this section have been performed. If a reboot has not been performed, the following commands should be executed by root:

```
modprobe xpmem
/etc/init.d/procset restart
/etc/init.d/arrayd restart
```

If you will be running MPT on a clustered system, these steps (or a reboot) must be performed for all hosts in the cluster.

Configuring Array Services

Array Services must be configured and running on all hosts in a cluster to perform the launch of MPI jobs. You can set up a simple Array Services configuration by executing the following two commands as root on all hosts of the cluster. List all host names on the arrayconfig command line:

/usr/sbin/arrayconfig -m host1 host2 ...
/etc/init.d/array restart

For a more elaborate configuration, consult the arrayconfig(1) and arrayd.conf(4) man pages and the "Installing and Configuring Array Services" section of the *Linux Resource Administration Guide*.

Adjusting File Descriptor Limits

On large hosts with hundreds of processors, MPI jobs require a large number of file descriptors. On these systems you might need to increase the system-wide limit on the number of open files. The default value for the file-limit resource is 1024. To change the default value for all users to 8192 file descriptors:

1. Add the following line to /etc/pam.d/login:

session required /lib/security/pam_limits.so

2. Add the following lines to /etc/security/limits.conf:

*	soft	nofile	8192
*	hard	nofile	8192

The default 1024 file descriptors will allow for approximately 199 MPI processes per host. Increasing the value to 8192 allows for more than 512 MPI processes per host.

If other login methods are used (ssh, rlogin, and so on), and the increased file descriptor limits are desired, the corresponding files in /etc/pam.d should be modified as well.

Adjusting Locked Memory Limits

The OFED-based InfiniBand software stacks require the resource limit for locked memory to be set to a high value.

Increase the user hard limit by adding the following line to
/etc/security/limits.conf:

* hard memlock unlimited

If you are running on a system with an SGI ProPack software release prior to SGI ProPack 5 Service Pack 1, you will also need to patch the Array Services startup script /etc/init.d/array to ensure that arrayd is running with a high "memlock" hard limit. This is done by the following sequence, executed as root:

```
sed -i.bak 's/ulimit -n/ulimit -l unlimited ; ulimit -n/' \
    /etc/init.d/array
/etc/init.d/array restart
```

Getting Started

This chapter provides procedures for building MPI applications. It provides examples of the use of the mpirun(1) command to launch MPI jobs. It also provides procedures for building and running SHMEM applications. It covers the following topics:

- "Compiling and Linking MPI Programs" on page 13
- "Running MPI Jobs with a Portable Batch System (PBS)" on page 16
- "Running MPI Jobs with Torque" on page 17
- "Compiling and Running SHMEM Applications" on page 18

Compiling and Linking MPI Programs

The default locations for the include files, the .so files, the .a files, and the mpirun command are pulled in automatically. Once the MPT RPM is installed as default, the commands to build an MPI-based application using the .so files are as follows:

• To compile using GNU compilers, choose one of the following commands:

```
% g++ -o myprog myprog.C -lmpi++ -lmpi
% gcc -o myprog myprog.c -lmpi
% g77 -I/usr/include -o myprog myprog.f -lmpi
```

• To compile programs with the Intel compiler, use the following commands:

<pre>% efc -o myprog myprog.f -lmpi</pre>	(Fortran - version 7.1)
<pre>% ecc -o myprog myprog.c -lmpi</pre>	(C - version 7.1)
<pre>% ifort -o myprog myprog.f -lmpi</pre>	(Fortran - version 8)
<pre>% icc -o myprog myprog.c -lmpi</pre>	(C - version 8)

The libmpi++.so library is compatible with code generated by $g_{++} 3.0$ or later compilers, as well as Intel C++ 8.0 or later compilers. If compatibility with previous g_{++} or C++ compilers is required, the libmpi++.so released with MPT 1.9 (or earlier) must be used.

Note: You must use the Intel compiler to compile Fortran 90 programs.

• To compile Fortran programs with the Intel compiler, enabling compile-time checking of MPI subroutine calls, insert a USE MPI statement near the beginning of each subprogram to be checked and use one of the following commands:

```
% efc -I/usr/include -o myprog myprog.f -lmpi (version 7.1)
% ifort -I/usr/include -o myprog myprog.f -lmpi (version 8)
```

Note: The above command line assumes a default installation; if you have installed MPT into a non-default location, replace /usr/include with the name of the relocated directory.

Using mpirun to Launch an MPI Application

You must use the mpirun command to start MPI applications. For complete specification of the command line syntax, see the mpirun(1) man page. This section summarizes the procedures for launching an MPI application.

Launching a Single Program on the Local Host

To run an application on the local host, enter the mpirun command with the -np argument. Your entry must include the number of processes to run and the name of the MPI executable file.

The following example starts three instances of the mtest application, which is passed an argument list (arguments are optional):

% mpirun -np 3 mtest 1000 "arg2"

Launching a Multiple Program, Multiple Data (MPMD) Application on the Local Host

You are not required to use a different host in each entry that you specify on the mpirun command. You can launch a job that has multiple executable files on the same host. In the following example, one copy of progl and five copies of prog2 are run on the local host. Both executable files use shared memory.

% mpirun -np 1 prog1 : 5 prog2

Launching a Distributed Application

You can use the mpirun command to launch a program that consists of any number of executable files and processes and you can distribute the program to any number of hosts. A host is usually a single machine, or it can be any accessible computer running Array Services software. For available nodes on systems running Array Services software, see the /usr/lib/array/arrayd.conf file.

You can list multiple entries on the mpirun command line. Each entry contains an MPI executable file and a combination of hosts and process counts for running it. This gives you the ability to start different executable files on the same or different hosts as part of the same MPI application.

The examples in this section show various ways to launch an application that consists of multiple MPI executable files on multiple hosts.

The following example runs ten instances of the a.out file on host_a:

% mpirun host_a -np 10 a.out

When specifying multiple hosts, you can omit the -np option and list the number of processes directly. The following example launches ten instances of fred on three hosts. fred has two input arguments.

% mpirun host_a, host_b, host_c 10 fred arg1 arg2

The following example launches an MPI application on different hosts with different numbers of processes and executable files:

% mpirun host_a 6 a.out : host_b 26 b.out

Using MPI-2 Spawn Functions to Launch an Application

To use the MPI-2 process creation functions MPI_Comm_spawn or MPI_Comm_spawn_multiple, you must specify the universe size by specifying the -up option on the mpirun command line. For example, the following command starts three instances of the mtest MPI application in a universe of size 10:

% mpirun -up 10 -np 3 mtest

By using one of the above MPI spawn functions, mtest can start up to seven more MPI processes.

When running MPI applications on partitioned Altix systems which use the MPI-2 MPI_Comm_spawn or MPI_Comm_spawn_multiple functions, it may be necessary to explicitly specify the partitions on which additional MPI processes may be launched. See the section "Launching Spawn Capable Jobs on Altix Partitioned Systems" on the mpirun(1) man page.

Running MPI Jobs with a Portable Batch System (PBS)

Often MPI applications are run from job scripts submitted through batch schedulers like PBS Professional. This section provides some details about how to properly set up PBS job scripts to run MPI applications.

PBS job scripts can specify needed resource allocations using the -1 option on a "#PBS" directive line. These lines will have the following form:

#PBS -l select=P:ncpus=T[:other options]

The value P should be set to the total number of MPI processes in the job, and the value T should be set to the number of OpenMP threads per process. For purely MPI jobs, T is 1. For more information on resource allocation options, see the pbs_resources(7) man page from the PBS Professional software distribution.

Each MPI application is executed with the mpiexec command that is delivered with the PBS Pro software packages. This is a wrapper script that assembles the correct host list and corresponding mpirun command before executing the assembled mpirun command. The basic syntax is, as follows:

mpiexec -n P ./a.out

where P is the total number of MPI processes in the application. This syntax applies whether running on a single host or a clustered system. See the mpiexec(1) man page for more details.

Process and thread pinning onto CPUs is especially important on ccNUMA systems like the SGI Altix 4700. Process pinning is performed automatically if PBS Professional is set up to run each application in a set of dedicated cpusets. In these cases, PBS Professional will set the PBS_CPUSET_DEDICATED environment variable to the value "YES". This has the same effect as setting MPI_DSM_DISTRIBUTE=ON. Process and thread pinning are also performed in all cases where omplace(1) is used.

Example 3-1 Run an MPI application with 512 Processes

To run an application with 512 processes, perform the following:

```
#PBS -l select=512:ncpus=1
mpiexec -n 512 ./a.out
```

Example 3-2 Run an MPI application with 512 Processes and Four OpenMP Threads per Process

To run an MPI application with 512 Processes and four OpenMP threads per process, perform the following:

```
#PBS -1 select=512:ncpus=4
mpiexec -n 512 omplace -nt 4 ./a.out
```

The mpiexec_mpt(1) command is provided by the SGI Message Passing Toolkit (MPT). The mpiexec_mpt command launches a MPT MPI program in a batch schedular-managed cluster environment. When running PBS Professional, mpiexec_mpt is an alternative to the mpiexec(1) command. Unlike the PBS Professional mpiexec command, mpiexec_mpt supports all MPT mpirun global options. The mpiexec_mpt command has a -tv option for use by MPT with the TotalView Debugger. For more information on using the mpiexec_mpt command -tv option, see "Using the TotalView Debugger with MPI programs" on page 29.

Running MPI Jobs with Torque

When running Torque, SGI recommends the MPT mpiexec_mpt(1) command to launch MPT MPI jobs.

The basic syntax is, as follows:

mpiexec_mpt -n P ./a.out

where P is the total number of MPI processes in the application. This syntax applies whether running on a single host or a clustered system. See the mpiexec_mpt(1) man page for more details.

The mpiexec_mpt command has a -tv option for use by MPT when running the TotalView Debugger with a batch scheduler like Torque. For more information on using the mpiexec_mpt command -tv option, see "Using the TotalView Debugger with MPI programs" on page 29.

Compiling and Running SHMEM Applications

To compile SHMEM programs with a GNU compiler, choose one of the following commands:

% g++ compute.C -lsma
% gcc compute.c -lsma
% g77 -I/usr/include compute.f -lsma

To compile SHMEM programs with the Intel compiler, use the following commands:

% ecc compute.C -lsma (version 7.1) % ecc compute.c -lsma (version 7.1) % efc compute.f -lsma (version 7.1) % icc compute.C -lsma (version 8) % icc compute.c -lsma (version 8) % ifort compute.f -lsma (version 8)

You must use mpirun to launch SHMEM applications. The NPES variable has no effect on SHMEM programs. To request the desired number of processes to launch, you must set the -np option on mpirun.

The SHMEM programming model supports single host SHMEM applications, as well as SHMEM applications that span multiple partitions. To launch a SHMEM application on more than one partition, use the multiple host mpirun syntax, such as the following:

% mpirun hostA, hostB -np 16 ./shmem_app

For more information, see the intro_shmem(3) man page.

Programming with SGI MPI

Portability is one of the main advantages MPI has over vendor-specific message passing software. Nonetheless, the MPI Standard offers sufficient flexibility for general variations in vendor implementations. In addition, there are often vendor specific programming recommendations for optimal use of the MPI library. This chapter addresses topics that are of interest to those developing or porting MPI applications to SGI systems. It covers the following topics:

- "Job Termination and Error Handling" on page 19
- "Signals" on page 20
- "Buffering" on page 21
- "Multithreaded Programming" on page 22
- "Interoperability with the SHMEM programming model" on page 22
- "Miscellaneous Features of SGI MPI" on page 23
- "Programming Optimizations" on page 23
- "Additional Programming Model Considerations" on page 26

Job Termination and Error Handling

This section describes the behavior of the SGI MPI implementation upon normal job termination. Error handling and characteristics of abnormal job termination are also described.

MPI_Abort

In the SGI MPI implementation, a call to MPI_Abort causes the termination of the entire MPI job, regardless of the communicator argument used. The error code value is returned as the exit status of the mpirun command. A stack traceback is displayed that shows where the program called MPI_Abort.

Error Handling

Section 7.2 of the MPI Standard describes MPI error handling. Although almost all MPI functions return an error status, an error handler is invoked before returning from the function. If the function has an associated communicator, the error handler associated with that communicator is invoked. Otherwise, the error handler associated with MPI_COMM_WORLD is invoked.

The SGI MPI implementation provides the following predefined error handlers:

- MPI_ERRORS_ARE_FATAL. The handler, when called, causes the program to abort on all executing processes. This has the same effect as if MPI_Abort were called by the process that invoked the handler.
- MPI_ERRORS_RETURN. The handler has no effect.

By default, the MPI_ERRORS_ARE_FATAL error handler is associated with MPI_COMM_WORLD and any communicators derived from it. Hence, to handle the error statuses returned from MPI calls, it is necessary to associate either the MPI_ERRORS_RETURN handler or another user defined handler with MPI_COMM_WORLD near the beginning of the application.

MPI_Finalize and Connect Processes

In the SGI implementation of MPI, all pending communications involving an MPI process must be complete before the process calls MPI_Finalize. If there are any pending send or recv requests that are unmatched or not completed, the application will hang in MPI_Finalize. For more details, see section 7.5 of the MPI Standard.

If the application uses the MPI-2 spawn functionality described in Chapter 5 of the MPI-2 Standard, there are additional considerations. In the SGI implementation, all MPI processes are connected. Section 5.5.4 of the MPI-2 Standard defines what is meant by connected processes. When the MPI-2 spawn functionality is used, MPI_Finalize is collective over all connected processes. Thus all MPI processes, both launched on the command line, or subsequently spawned, synchronize in MPI_Finalize.

Signals

In the SGI implementation, MPI processes are UNIX processes. As such, the general rule regarding handling of signals applies as it would to ordinary UNIX processes.

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In addition, the SIGURG and SIGUSR1 signals can be propagated from the mpirun process to the other processes in the MPI job, whether they belong to the same process group on a single host, or are running across multiple hosts in a cluster. To make use of this feature, the MPI program must have a signal handler that catches SIGURG or SIGUSR1. When the SIGURG or SIGUSR1 signals are sent to the mpirun process ID, the mpirun process catches the signal and propagates it to all MPI processes.

Buffering

Most MPI implementations use buffering for overall performance reasons and some programs depend on it. However, you should not assume that there is any message buffering between processes because the MPI Standard does not mandate a buffering strategy. Table 4-1 on page 21 illustrates a simple sequence of MPI operations that cannot work unless messages are buffered. If sent messages were not buffered, each process would hang in the initial call, waiting for an MPI_Recv call to take the message.

Because most MPI implementations do buffer messages to some degree, a program like this does not usually hang. The MPI_Send calls return after putting the messages into buffer space, and the MPI_Recv calls get the messages. Nevertheless, program logic like this is not valid by the MPI Standard. Programs that require this sequence of MPI calls should employ one of the buffer MPI send calls, MPI_Bsend or MPI_Ibsend.

Table 4-1 Outline of Improper Dependence on Buffering

Process 1	Process 2
MPI_Send(2,)	MPI_Send(1,)
<pre>MPI_Recv(2,)</pre>	<pre>MPI_Recv(1,)</pre>

By default, the SGI implementation of MPI uses buffering under most circumstances. Short messages (64 or fewer bytes) are always buffered. Longer messages are also buffered, although under certain circumstances buffering can be avoided. For performance reasons, it is sometimes desirable to avoid buffering. For further information on unbuffered message delivery, see "Programming Optimizations" on page 23.

Multithreaded Programming

SGI MPI supports hybrid programming models, in which MPI is used to handle one level of parallelism in an application, while POSIX threads or OpenMP processes are used to handle another level. When mixing OpenMP with MPI, for performance reasons it is better to consider invoking MPI functions only outside parallel regions, or only from within master regions. When used in this manner, it is not necessary to initialize MPI for thread safety. You can use MPI_Init to initialize MPI. However, to safely invoke MPI functions from any OpenMP process or when using Posix threads, MPI must be initialized with MPI_Init_thread.

When using MPI_Thread_init() with the threading level MPI_THREAD_MULTIPLE, link your program with -lmpi_mt instead of -lmpi. See the mpi(1) man page for more information about compiling and linking MPI programs.

Interoperability with the SHMEM programming model

You can mix SHMEM and MPI message passing in the same program. The application must be linked with both the SHMEM and MPI libraries. Start with an MPI program that calls MPI_Init and MPI_Finalize.

When you add SHMEM calls, the PE numbers are equal to the MPI rank numbers in MPI_COMM_WORLD. Do not call start_pes() in a mixed MPI and SHMEM program.

When running the application across a cluster, some MPI processes may not be able to communicate with certain other MPI processes when using SHMEM functions. You can use the shmem_pe_accessible and shmem_addr_accessible functions to determine whether a SHMEM call can be used to access data residing in another MPI process. Because the SHMEM model functions only with respect to MPI_COMM_WORLD, these functions cannot be used to exchange data between MPI processes that are connected via MPI intercommunicators returned from MPI-2 spawn related functions.

SHMEM get and put functions are thread safe. SHMEM collective and synchronization functions are not thread safe unless different threads use different pSync and pWork arrays.

For more information about the SHMEM programming model, see the intro_shmem man page.

Miscellaneous Features of SGI MPI

This section describes other characteristics of the SGI MPI implementation that might be of interest to application developers.

stdin/stdout/stderr

In this implementation, stdin is enabled for only those MPI processes with rank 0 in the first MPI_COMM_WORLD (which does not need to be located on the same host as mpirun). stdout and stderr results are enabled for all MPI processes in the job, whether launched via mpirun, or via one of the MPI-2 spawn functions.

MPI_Get_processor_name

The MPI_Get_processor_name function returns the Internet host name of the computer on which the MPI process invoking this subroutine is running.

Programming Optimizations

This section describes ways in which the MPI application developer can best make use of optimized features of SGI's MPI implementation. Following recommendations in this section might require modifications to your MPI application.

Using MPI Point-to-Point Communication Routines

MPI provides for a number of different routines for point-to-point communication. The most efficient ones in terms of latency and bandwidth are the blocking and nonblocking send/receive functions (MPI_Send, MPI_Isend, MPI_Recv, and MPI_Irecv).

Unless required for application semantics, the synchronous send calls (MPI_Ssend and MPI_Issend) should be avoided. The buffered send calls (MPI_Bsend and MPI_Ibsend) should also usually be avoided as these double the amount of memory copying on the sender side. The ready send routines (MPI_Rsend and MPI_Irsend) are treated as standard MPI_Send and MPI_Isend in this implementation. Persistent requests do not offer any performance advantage over standard requests in this implementation.

Using MPI Collective Communication Routines

The MPI collective calls are frequently layered on top of the point-to-point primitive calls. For small process counts, this can be reasonably effective. However, for higher process counts (32 processes or more) or for clusters, this approach can become less efficient. For this reason, a number of the MPI library collective operations have been optimized to use more complex algorithms.

Some collectives have been optimized for use with clusters. In these cases, steps are taken to reduce the number of messages using the relatively slower interconnect between hosts.

Two of the collective operations have been optimized for use with shared memory. The barrier operation has also been optimized to use hardware fetch operations (fetchops). The MPI_Alltoall routines also use special techniques to avoid message buffering when using shared memory. For more details, see "Avoiding Message Buffering — Single Copy Methods" on page 25. Table 4-2 on page 24, lists the MPI collective routines optimized in this implementation.

Routine	Optimized for Clusters	Optimized for Shared Memory
MPI_Alltoall	Yes	Yes
MPI_Barrier	Yes	Yes
MPI_Allreduce	Yes	No
MPI_Bcast	Yes	No

 Table 4-2 Optimized MPI Collectives

Note: These collectives are optimized across partitions by using the XPMEM driver which is explained in Chapter 7, "Run-time Tuning". These collectives (except MPI_Barrier) will try to use single-copy by default for large transfers unless MPI_DEFAULT_SINGLE_COPY_OFF is specified.

Using MPI_Pack/MPI_Unpack

While MPI_Pack and MPI_Unpack are useful for porting PVM codes to MPI, they essentially double the amount of data to be copied by both the sender and receiver. It

is generally best to avoid the use of these functions by either restructuring your data or using derived data types. Note, however, that use of derived data types may lead to decreased performance in certain cases.

Avoiding Derived Data Types

In general, you should avoid derived data types when possible. In the SGI implementation, use of derived data types does not generally lead to performance gains. Use of derived data types might disable certain types of optimizations (for example, unbuffered or single copy data transfer).

Avoiding Wild Cards

The use of wild cards (MPI_ANY_SOURCE, MPI_ANY_TAG) involves searching multiple queues for messages. While this is not significant for small process counts, for large process counts the cost increases quickly.

Avoiding Message Buffering — Single Copy Methods

One of the most significant optimizations for bandwidth sensitive applications in the MPI library is single copy optimization, avoiding the use of shared memory buffers. However, as discussed in "Buffering" on page 21, some incorrectly coded applications might hang because of buffering assumptions. For this reason, this optimization is not enabled by default for MPI_send, but can be turned on by the user at run time by using the MPI_BUFFER_MAX environment variable. The following steps can be taken by the application developer to increase the opportunities for use of this unbuffered pathway:

- The MPI data type on the send side must be a contiguous type.
- The sender and receiver MPI processes must reside on the same host or, in the case of a partitioned system, the processes may reside on any of the partitions.
- The sender data must be globally accessible by the receiver. The SGI MPI implementation allows data allocated from the static region (common blocks), the private heap, and the stack region to be globally accessible. In addition, memory allocated via the MPI_Alloc_mem function or the SHMEM symmetric heap accessed via the shpalloc or shmalloc functions is globally accessible.

Certain run-time environment variables must be set to enable the unbuffered, single copy method. For more details on how to set the run-time environment, see "Avoiding Message Buffering – Enabling Single Copy" on page 41.

Note: With the Intel 7.1 compiler, ALLOCATABLE arrays are not eligible for single copy, since they do not reside in a globally accessible memory region. This restriction does not apply when using the Intel 8.0/8.1 compilers.

Managing Memory Placement

SGI systems have a ccNUMA memory architecture. For single process and small multiprocess applications, this architecture behaves similarly to flat memory architectures. For more highly parallel applications, memory placement becomes important. MPI takes placement into consideration when laying out shared memory data structures, and the individual MPI processes' address spaces. In general, it is not recommended that the application programmer try to manage memory placement explicitly. There are a number of means to control the placement of the application at run time, however. For more information, see Chapter 7, "Run-time Tuning" on page 39.

Using Global Shared Memory

The MPT software includes the Global Shared Memory (GSM) Feature. This feature allows users to allocate globally accessible shared memory from within an MPI or SHMEM program. The GSM feature can be used to provide shared memory access across partitioned Altix systems and additional memory placement options within a single host configuration.

User-callable functions are provided to allocate a global shared memory segment, free that segment, and provide information about the segment. Once allocated, the application can use this new global shared memory segment via standard loads and stores, just as if it were a System V shared memory segment. For more information, see the GSM_Intro or GSM_Alloc man pages.

Additional Programming Model Considerations

A number of additional programming options might be worth consideration when developing MPI applications for SGI systems. For example, the SHMEM programming model can provide a means to improve the performance of latency-sensitive sections of an application. Usually, this requires replacing MPI send/recv calls with shmem_put/shmem_get and shmem_barrier calls. The SHMEM programming model can deliver significantly lower latencies for short messages than traditional MPI calls. As an alternative to shmem_get/shmem_put calls, you might consider the MPI-2 MPI_Put/ MPI_Get functions. These provide almost the same performance as the SHMEM calls, while providing a greater degree of portability.

Alternately, you might consider exploiting the shared memory architecture of SGI systems by handling one or more levels of parallelism with OpenMP, with the coarser grained levels of parallelism being handled by MPI. Also, there are special ccNUMA placement considerations to be aware of when running hybrid MPI/OpenMP applications. For further information, see Chapter 7, "Run-time Tuning" on page 39.

Chapter 5

Debugging MPI Applications

Debugging MPI applications can be more challenging than debugging sequential applications. This chapter presents methods for debugging MPI applications. It covers the following topics:

- "MPI Routine Argument Checking" on page 29
- "Using the TotalView Debugger with MPI programs" on page 29
- "Using idb and gdb with MPI programs" on page 30

MPI Routine Argument Checking

By default, the SGI MPI implementation does not check the arguments to some performance-critical MPI routines such as most of the point-to-point and collective communication routines. You can force MPI to always check the input arguments to MPI functions by setting the MPI_CHECK_ARGS environment variable. However, setting this variable might result in some degradation in application performance, so it is not recommended that it be set except when debugging.

Using the TotalView Debugger with MPI programs

The syntax for running SGI MPI with the TotalView Debugger (TVD) from TotalView Technologies is, as follows:

% totalview mpirun -a -np 4 a.out

Note that TVD is not expected to operate with MPI processes started via the MPI_Comm_spawn or MPI_Comm_spawn_multiple functions.

The MPT mpiexec_mpt(1) command has a -tv option for use by MPT with the TotalView Debugger. Note that the PBS Professional mpiexec(1) command does not support the -tv option.

To run an MPT MPI job with TotalView without a batch scheduler (same as the above example), perform the following:

% totalview mpirun -a -np 4 a.out

To run an MPT MPI job with Total View Debugger with a batch schduler, such as, PBS Professional or Torque, perform the following:

% mpiexec_mpt -tv -np 4 a.out

Using idb and gdb with MPI programs

Because the idb and gdb debuggers are designed for sequential, non-parallel applications, they are generally not well suited for use in MPI program debugging and development. However, the use of the MPI_SLAVE_DEBUG_ATTACH environment variable makes these debuggers more usable.

If you set the MPI_SLAVE_DEBUG_ATTACH environment variable to a global rank number, the MPI process sleeps briefly in startup while you use idb or gdb to attach to the process. A message is printed to the screen, telling you how to use idb or gdb to attach to the process.

Similarly, if you want to debug the MPI daemon, setting MPI_DAEMON_DEBUG_ATTACH sleeps the daemon briefly while you attach to it.

Profiling MPI Applications

This chapter describes the use of profiling tools to obtain performance information. Compared to the performance analysis of sequential applications, characterizing the performance of parallel applications can be challenging. Often it is most effective to first focus on improving the performance of MPI applications at the single process level.

It may also be important to understand the message traffic generated by an application. A number of tools can be used to analyze this aspect of a message passing application's performance, including Performance Co-Pilot and various third party products. In this chapter, you can learn how to use these various tools with MPI applications. It covers the following topics:

- "Using Profiling Tools with MPI Applications" on page 31
- "Profiling Interface" on page 32
- "MPI Internal Statistics" on page 33
- "Performance Co-Pilot" on page 34

Using Profiling Tools with MPI Applications

Two of the most common SGI profiling tools are profile.pl and histx+. The following sections describe how to invoke these tools. Performance Co-Pilot tools and tips for writing your own tools are also included.

You can also use the perfcatch utility to profile the performance of an MPI program. For more information, see Chapter 8, "MPI Performance Profiling" on page 51.

profile.pl

You can use profile.pl to obtain procedure level profiling as well as information about the hardware performance monitors. For further information, see the profile.pl(1) and pfmon(1) man pages.

General format:

% mpirun mpirun_entry_object [mpirun_entry_object ...] profile.pl [profile.pl_options] executable

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Example:

% mpirun -np 4 profile.pl -s1 -c4,5 -N 1000 ./a.out

histx+

histx+ is a small set of tools that can assist with performance analysis and bottlenect identification.

General formats for histx (Histogram) and lipfpm (Linux IPF Performance Monitor):

% mpirun -np 4 histx [histx_options] ./a.out

% lipfpm [lipfpm_options] mmpirun -np 4 ./a.out

Examples:

% mpirun -np 4 histx -f -o histx.out ./a.out

% lipfpm -f -e LOADS_RETIRED -e STORES_RETIRED mpirun -np 4 ./a.out

Profiling Interface

You can write your own profiling by using the MPI-1 standard PMPI_* calls. In addition, either within your own profiling library or within the application itself you can use the MPI_Wtime function call to time specific calls or sections of your code.

The following example is actual output for a single rank of a program that was run on 128 processors, using a user-created profiling library that performs call counts and timings of common MPI calls. Notice that for this rank most of the MPI time is being spent in MPI_Waitall and MPI_Allreduce.

```
Total job time 2.203333e+02 sec
Total MPI processes 128
Wtime resolution is 8.000000e-07 sec
activity on process rank 0
comm_rank calls 1 time 8.800002e-06
get_count calls 0 time 0.000000e+00
ibsend calls 0 time 0.000000e+00
```

```
0
probe calls
                    time 0.000000e+00
recv calls
            0
                    time 0.00000e+00
                                    avg datacnt 0 waits 0
                                                                wait time 0.00000e+00
irecv calls 22039 time 9.76185e-01
                                     datacnt 23474032 avg datacnt 1065
send calls
            0
                   time 0.000000e+00
            0
ssend calls
                    time 0.000000e+00
isend calls
            22039 time 2.950286e+00
wait calls
            0 time 0.00000e+00
                                     avg datacnt 0
waitall calls 11045 time 7.73805e+01
                                     # of Reqs 44078 avg data cnt 137944
barrier calls 680
                    time 5.133110e+00
alltoall calls 0 time 0.0e+00
                                     avg datacnt 0
alltoallv calls 0
                  time 0.000000e+00
reduce calls 0
                   time 0.000000e+00
allreduce calls 4658 time 2.072872e+01
bcast calls 680 time 6.915840e-02
gather calls 0
                   time 0.000000e+00
gatherv calls 0
                    time 0.000000e+00
scatter calls 0
                    time 0.000000e+00
scatterv calls 0
                    time 0.000000e+00
activity on process rank 1
. . .
```

MPI Internal Statistics

MPI keeps track of certain resource utilization statistics. These can be used to determine potential performance problems caused by lack of MPI message buffers and other MPI internal resources.

To turn on the displaying of MPI internal statistics, use the MPI_STATS environment variable or the -stats option on the mpirun command. MPI internal statistics are always being gathered, so displaying them does not cause significant additional overhead. In addition, one can sample the MPI statistics counters from within an application, allowing for finer grain measurements. If the MPI_STATS_FILE variable is set, when the program completes, the internal statistics will be written to the file specified by this variable. For information about these MPI extensions, see the mpi_stats man page.

These statistics can be very useful in optimizing codes in the following ways:

• To determine if there are enough internal buffers and if processes are waiting (retries) to aquire them

• To determine if single copy optimization is being used for point-to-point or collective calls

For additional information on how to use the MPI statistics counters to help tune the run-time environment for an MPI application, see Chapter 7, "Run-time Tuning" on page 39.

Performance Co-Pilot

In addition to the tools described in the preceding sections, you can also use the MPI agent for Performance Co-Pilot to profile your application. The two additional Performance Co-Pilot tools specifically designed for MPI are mpivis and mpimon. These tools do not use trace files and can be used live or can be logged for later replay.

Following are examples of the mpivis and mpimon tools.

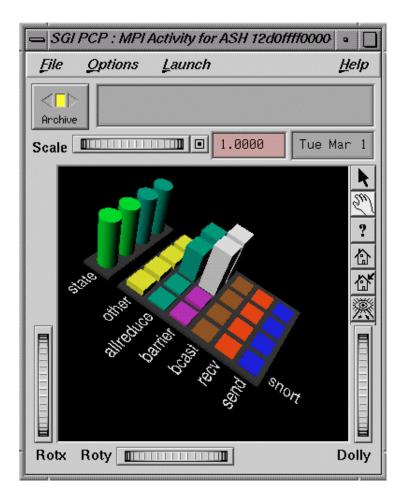


Figure 6-1 mpivis Tool

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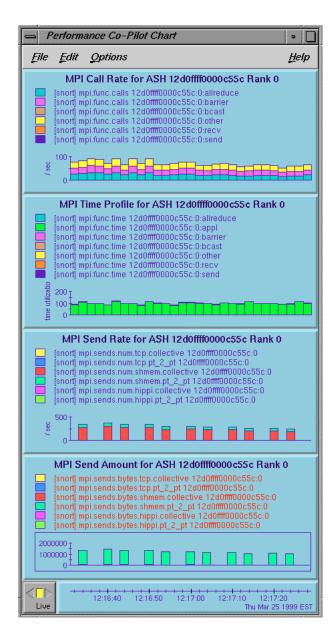


Figure 6-2 mpimon Tool

Third Party Products

Two third party tools that you can use with the SGI MPI implementation are Vampir from Pallas (www.pallas.com) and Jumpshot, which is part of the MPICH distribution. Both of these tools are effective for smaller, short duration MPI jobs. However, the trace files these tools generate can be enormous for longer running or highly parallel jobs. This causes a program to run more slowly, but even more problematic is that the tools to analyze the data are often overwhelmed by the amount of data.

Chapter 7

Run-time Tuning

This chapter discusses ways in which the user can tune the run-time environment to improve the performance of an MPI message passing application on SGI computers. None of these ways involve application code changes. This chapter covers the following topics:

- "Reducing Run-time Variability" on page 39
- "Tuning MPI Buffer Resources" on page 40
- "Avoiding Message Buffering Enabling Single Copy" on page 41
- "Memory Placement and Policies" on page 42
- "Tuning MPI/OpenMP Hybrid Codes" on page 45
- "Tuning for Running Applications Across Multiple Hosts" on page 46
- "Tuning for Running Applications over the InfiniBand Interconnect" on page 48
- "Suspending MPI Jobs" on page 49

Reducing Run-time Variability

One of the most common problems with optimizing message passing codes on large shared memory computers is achieving reproducible timings from run to run. To reduce run-time variability, you can take the following precautions:

- Do not oversubscribe the system. In other words, do not request more CPUs than are available and do not request more memory than is available. Oversubscribing causes the system to wait unnecessarily for resources to become available and leads to variations in the results and less than optimal performance.
- Avoid interference from other system activity. The Linux kernel uses more memory on node 0 than on other nodes (node 0 is called the kernel node in the following discussion). If your application uses almost all of the available memory per processor, the memory for processes assigned to the kernel node can unintentionally spill over to nonlocal memory. By keeping user applications off the kernel node, you can avoid this effect.

Additionally, by restricting system daemons to run on the kernel node, you can also deliver an additional percentage of each application CPU to the user.

- Avoid interference with other applications. You can use cpusets or cpumemsets to address this problem also. You can use cpusets to effectively partition a large, distributed memory host in a fashion that minimizes interactions between jobs running concurrently on the system. See the *Linux Resource Administration Guide* for information about cpusets and cpumemsets.
- On a quiet, dedicated system, you can use dplace or the MPI_DSM_CPULIST shell variable to improve run-time performance repeatability. These approaches are not as suitable for shared, nondedicated systems.
- Use a batch scheduler; for example, LSF from Platform Computing or PBSpro from Veridan. These batch schedulers use cpusets to avoid oversubscribing the system and possible interference between applications.

Tuning MPI Buffer Resources

By default, the SGI MPI implementation buffers messages whose lengths exceed 64 bytes. Longer messages are buffered in a shared memory region to allow for exchange of data between MPI processes. In the SGI MPI implementation, these buffers are divided into two basic pools.

- For messages exchanged between MPI processes within the same host or between partitioned systems when using the XPMEM driver, buffers from the "per process" pool (called the "per proc" pool) are used. Each MPI process is allocated a fixed portion of this pool when the application is launched. Each of these portions is logically partitioned into 16-KB buffers.
- For MPI jobs running across multiple hosts, a second pool of shared memory is available. Messages exchanged between MPI processes on different hosts use this pool of shared memory, called the "per host" pool. The structure of this pool is somewhat more complex than the "per proc" pool.

For an MPI job running on a single host, messages that exceed 64 bytes are handled as follows. For messages with a length of 16 KB or less, the sender MPI process buffers the entire message. It then delivers a message header (also called a control message) to a mailbox, which is polled by the MPI receiver when an MPI call is made. Upon finding a matching receive request for the sender's control message, the receiver copies the data out of the shared memory buffer into the application buffer indicated in the receive request. The receiver then sends a message header back to the sender process, indicating that the shared memory buffer is available for reuse. Messages whose length exceeds 16 KB are broken down into 16-KB chunks, allowing the sender and receiver to overlap the copying of data to and from shared memory in a pipeline fashion.

Because there is a finite number of these shared memory buffers, this can be a constraint on the overall application performance for certain communication patterns. You can use the MPI_BUFS_PER_PROC shell variable to adjust the number of buffers available for the "per proc" pool. Similarly, you can use the MPI_BUFS_PER_HOST shell variable to adjust the "per host" pool. You can use the MPI statistics counters to determine if retries for these shared memory buffers are occurring.

For information on the use of these counters, see "MPI Internal Statistics" on page 33. In general, you can avoid excessive numbers of retries for buffers by increasing the number of buffers for the "per proc" pool or "per host" pool. However, you should keep in mind that increasing the number of buffers does consume more memory. Also, increasing the number of "per proc" buffers does potentially increase the probability for cache pollution (that is, the excessive filling of the cache with message buffers). Cache pollution can result in degraded performance during the compute phase of a message passing application.

There are additional buffering considerations to take into account when running an MPI job across multiple hosts. For further discussion of multihost runs, see "Tuning for Running Applications Across Multiple Hosts" on page 46.

For further discussion on programming implications concerning message buffering, see "Buffering" on page 21.

Avoiding Message Buffering – Enabling Single Copy

For message transfers between MPI processes within the same host or transfers between partitions, it is possible under certain conditions to avoid the need to buffer messages. Because many MPI applications are written assuming infinite buffering, the use of this unbuffered approach is not enabled by default for MPI_Send. This section describes how to activate this mechanism by default for MPI_Send.

For MPI_Isend, MPI_Sendrecv, MPI_Alltoall, MPI_Bcast, MPI_Allreduce, and MPI_Reduce, this optimization is enabled by default for large message sizes. To disable this default single copy feature used for the collectives, use the MPI_DEFAULT_SINGLE_COPY_OFF environment variable.

Using the XPMEM Driver for Single Copy Optimization

MPI takes advantage of the XPMEM driver to support single copy message transfers between two processes within the same host or across partitions.

Enabling single copy transfers may result in better performance, since this technique improves MPI's bandwidth. However, single copy transfers may introduce additional synchronization points, which can reduce application performance in some cases.

The threshold for message lengths beyond which MPI attempts to use this single copy method is specified by the MPI_BUFFER_MAX shell variable. Its value should be set to the message length in bytes beyond which the single copy method should be tried. In general, a value of 2000 or higher is beneficial for many applications.

During job startup, MPI uses the XPMEM driver (via the xpmem kernel module) to map memory from one MPI process to another. The mapped areas include the static (BSS) region, the private heap, the stack region, and optionally the symmetric heap region of each process.

Memory mapping allows each process to directly access memory from the address space of another process. This technique allows MPI to support single copy transfers for contiguous data types from any of these mapped regions. For these transfers, whether between processes residing on the same host or across partitions, the data is copied using a bcopy process. A bcopy process is also used to transfer data between two different executable files on the same host or two different executable files across partitions. For data residing outside of a mapped region (a /dev/zero region, for example), MPI uses a buffering technique to transfer the data.

Memory mapping is enabled by default. To disable it, set the MPI_MEMMAP_OFF environment variable. Memory mapping must be enabled to allow single-copy transfers, MPI-2 one-sided communication, support for the SHMEM model, and certain collective optimizations.

Memory Placement and Policies

The MPI library takes advantage of NUMA placement functions that are available. Usually, the default placement is adequate. Under certain circumstances, however, you might want to modify this default behavior. The easiest way to do this is by setting one or more MPI placement shell variables. Several of the most commonly used of these variables are discribed in the following sections. For a complete listing of memory placement related shell variables, see the MPI(1) man page.

MPI_DSM_CPULIST

The MPI_DSM_CPULIST shell variable allows you to manually select processors to use for an MPI application. At times, specifying a list of processors on which to run a job can be the best means to insure highly reproducible timings, particularly when running on a dedicated system.

This setting is treated as a comma and/or hyphen delineated ordered list that specifies a mapping of MPI processes to CPUs. If running across multiple hosts, the per host components of the CPU list are delineated by colons. Within hyphen delineated lists CPU striding may be specified by placing "/#" after the list where "#" is the stride distance.

Note: This feature should not be used with MPI applications that use either of the MPI-2 spawn related functions.

Examples of settings are as follows:

Value	CPU Assignment
8,16,32	Place three MPI processes on CPUs 8, 16, and 32.
32,16,8	Place the MPI process rank zero on CPU 32, one on 16, and two on CPU 8.
8-15/2	Place the MPI processes 0 through 3 strided on CPUs 8, 10, 12, and 14
8-15,32-39	Place the MPI processes 0 through 7 on CPUs 8 to 15. Place the MPI processes 8 through 15 on CPUs 32 to 39.
39-32,8-15	Place the MPI processes 0 through 7 on CPUs 39 to 32. Place the MPI processes 8 through 15 on CPUs 8 to 15.
8-15:16-23	Place the MPI processes 0 through 7 on the first host on CPUs 8 through 15. Place MPI processes 8 through 15 on CPUs 16 to 23 on the second host.

Note that the process rank is the MPI_COMM_WORLD rank. The interpretation of the CPU values specified in the MPI_DSM_CPULIST depends on whether the MPI job is being run within a cpuset. If the job is run outside of a cpuset, the CPUs specify *cpunum* values beginning with 0 and up to the number of CPUs in the system minus one. When running within a cpuset, the default behavior is to interpret the CPU values as relative processor numbers within the cpuset.

The number of processors specified should equal the number of MPI processes that will be used to run the application. The number of colon delineated parts of the list must equal the number of hosts used for the MPI job. If an error occurs in processing the CPU list, the default placement policy is used.

MPI_DSM_DISTRIBUTE

Use the MPI_DSM_DISTRIBUTE shell variable to ensure that each MPI process will get a physical CPU and memory on the node to which it was assigned. If this environment variable is used without specifying an MPI_DSM_CPULIST variable, it will cause MPI to assign MPI ranks starting at logical CPU 0 and incrementing until all ranks have been placed. Therefore, it is recommended that this variable be used only if running within a cpumemset or on a dedicated system.

MPI_DSM_PPM

The MPI_DSM_PPM shell variable allows you to specify the number of MPI processes to be placed on a node. Memory bandwidth intensive applications can benefit from placing fewer MPI processes on each node of a distributed memory host. On SGI Altix 3000 systems, setting MPI_DSM_PPM to 1 places one MPI process on each node.

MPI_DSM_VERBOSE

Setting the MPI_DSM_VERBOSE shell variable directs MPI to display a synopsis of the NUMA placement options being used at run time.

Using dplace for Memory Placement

The dplace tool offers another means of specifying the placement of MPI processes within a distributed memory host. The dplace tool and MPI interoperate to allow MPI to better manage placement of certain shared memory data structures when dplace is used to place the MPI job.

For instructions on how to use dplace with MPI, see the dplace(1) man page and the *Linux Application Tuning Guide*.

Tuning MPI/OpenMP Hybrid Codes

A hybrid MPI/OpenMP application is one in which each MPI process itself is a parallel threaded program. These programs often exploit the OpenMP parallelism at the loop level while also implementing a higher level parallel algorithm using MPI.

Many parallel applications perform better if the MPI processes and the threads within them are pinned to particular processors for the duration of their execution. For ccNUMA systems, this ensures that all local, non-shared memory is allocated on the same memory node as the processor referencing it. For all systems, it can ensure that some or all of the OpenMP threads stay on processors that share a bus or perhaps a processor cache, which can speed up thread synchronization.

MPT provides the omplace(1) command to help with the placement of OpenMP threads within an MPI program. The omplace command causes the threads in a hybrid MPI/OpenMP job to be placed on unique CPUs within the containing cpuset. For example, the threads in a 2-process MPI program with 2 threads per process would be placed as follows:

rank 0 thread 0 on CPU 0 rank 0 thread 1 on CPU 1 rank 1 thread 0 on CPU 2 rank 1 thread 1 on CPU 3

The CPU placement is performed by dynamically generating a dplace(1) placement file and invoking dplace.

For detailed syntax and a number of examples, see the omplace(1) man page. For more information on dplace, see the dplace(1) man page. For information on using cpusets, see the *Linux Resource Administration Guide*. For more information on using dplace, see the *Linux Application Tuning Guide*.

Example 7-1 How to Run a Hybrid MPI/OpenMP Application

Here is an example of how to run a hybrid MPI/OpenMP application with eight MPI processes that are two-way threaded on two hosts:

mpirun host1,host2 -np 4 omplace -nt 2 ./a.out

When using the PBS batch scheduler to schedule the a hybrid MPI/OpenMP job as shown in Example 7-1 on page 45, use the following resource allocation specification:

#PBS -1 select=8:ncpus=2

And use the following mpiexec command with the above example:

mpiexec -n 8 omplace -nt 2 ./a.out

For more information about running MPT programs with PBS, see"Running MPI Jobs with a Portable Batch System (PBS)" on page 16.

Tuning for Running Applications Across Multiple Hosts

When you are running an MPI application across a cluster of hosts, there are additional run-time environment settings and configurations that you can consider when trying to improve application performance.

Systems can use the XPMEM interconnect to cluster hosts as partitioned systems, or use the Voltaire InfiniBand interconnect or TCP/IP as the multihost interconnect.

When launched as a distributed application, MPI probes for these interconnects at job startup. For details of launching a distributed application, see "Launching a Distributed Application" on page 15. When a high performance interconnect is detected, MPI attempts to use this interconnect if it is available on every host being used by the MPI job. If the interconnect is not available for use on every host, the library attempts to use the next slower interconnect until this connectivity requirement is met. Table 7-1 on page 46 specifies the order in which MPI probes for available interconnects.

 Table 7-1 Inquiry Order for Available Interconnects

Interconnect	Default Order of Selection	Environment Variable to Require Use
XPMEM	1	MPI_USE_XPMEM
InfiniBand	2	MPI_USE_IB
TCP/IP	3	MPI_USE_TCP

The third column of Table 7-1 on page 46 also indicates the environment variable you can set to pick a particular interconnect other than the default.

In general, to insure the best performance of the application, you should allow MPI to pick the fastest available interconnect.

In addition to the choice of interconnect, you should know that multihost jobs may use different buffers from those used by jobs run on a single host. In the SGI implementation of MPI, the XPMEM interconnect uses the "per proc" buffers while the InfiniBand and TCP interconnects use the "per host" buffers. The default setting for the number of buffers per proc or per host might be too low for many applications. You can determine whether this setting is too low by using the MPI statistics described earlier in this section.

When using the TCP/IP interconnect, unless specified otherwise, MPI uses the default IP adapter for each host. To use a nondefault adapter, enter the adapter-specific host name on the mpirun command line.

When using the InfiniBand interconnect, MPT applications may not execute a fork() or system() call. The InfiniBand driver produces undefined results when an MPT process using InfiniBand forks.

MPI_USE_IB

Requires the MPI library to use the InfiniBand driver as the interconnect when running across multiple hosts or running with multiple binaries. MPT requires the ibhost software stack from Voltaire when the InfiniBand interconnect is used. If InfiniBand is used, the MPI_COREDUMP environment variable is forced to INHIBIT, to comply with the InfiniBand driver restriction that no fork()s may occur after InfiniBand resources have been allocated. Default: Not set

MPI_IB_RAILS

If the MPI library uses the InfiniBand driver as the inter-host interconnect and this is set to equal 1, then the MPI library will use special low latency and higher bandwidth InfiniBand code paths. If this is set to 2, the library will try to make use of multiple available separate InfiniBand fabrics and split its traffic across them. If the separate InfiniBand fabrics do not have unique subnet IDs, then the rail-config utility is required. It must be run by the system administrator to enable the library to correctly use the separate fabrics. Default: 1 on all SGI Altix systems.

MPI_IB_SINGLE_COPY_BUFFER_MAX

When MPI transfers data over InfiniBand, if the size of the cumulative data is greater than this value then MPI will attempt to send the data directly between the processes's buffers and not through intermediate buffers inside the MPI library. Default: 32767

For more information on these environment variables, see the "ENVIRONMENT VARIABLES" section of the mpi(1) man page.

Tuning for Running Applications over the InfiniBand Interconnect

When running an MPI application across a cluster of hosts using the InfiniBand interconnect, there are additional run-time environmental settings that you can consider to improve application performance, as follows:

MPI_NUM_QUICKS

Controls the number of other ranks that a rank can receive from over InfiniBand using a short message fast path. This is 8 by default and can be any value between 0 and 32.

MPI_NUM_MEMORY_REGIONS

For zero-copy sends over the InfiniBand interconnect, MPT keeps a cache of application data buffers registered for these transfers. This environmental variable controls the size of the cache. It is 8 by default and can be any value between 0 and 32. If the application rarely reuses data buffers, it may make sense to set this value to 0 to avoid cache trashing.

MPI_CONNECTIONS_THRESHOLD

For very large MPI jobs, the time and resource cost to create a connection between every pair of ranks at job start time may be prodigious. When the number of ranks is at least this value, the MPI library will create InfiniBand connections lazily on a demand basis. The default is 2048 ranks.

MPI_CTRL_RING

When the MPI library is in lazy connection mode (see "MPI_CONNECTIONS_THRESHOLD" on page 48), it normally sends connection control messages directly between the involved ranks. This may create excessive load on the administration links between the involved hosts. When the number of ranks is at least the value of this variable, the MPI library will use a throttled control ring between the hosts for this traffic. The default is 8192 ranks.

MPI_IB_PAYLOAD

When the MPI library uses the InfiniBand fabric, it allocates some amount of memory for each message header that it uses for InfiniBand. If the size of data to be sent is not greater than this amount minus 64 bytes for the actual header, the data is inlined with the header. If the size is greater than this value, then the message is sent through remote direct memory access (RDMA) operations. The default is 16384 bytes.

Suspending MPI Jobs

MPI software from SGI can internally use the XPMEM kernel module to provide direct access to data on remote partitions and to provide single copy operations to local data. Any pages used by these operations are prevented from paging by the XPMEM kernel module. If an administrator needs to temporarily suspend a MPI application to allow other applications to run, they can unpin these pages so they can be swapped out and made available for other applications.

Each process of a MPI application which is using the XPMEM kernel module will have a /proc/xpmem/pid file associated with it. The number of pages owned by this process which are prevented from paging by XPMEM can be displayed by concatenating the /proc/xpmem/pid file, for example:

```
# cat /proc/xpmem/5562
```

```
pages pinned by XPMEM: 17
```

To unpin the pages for use by other processes, the administrator must first suspend all the processes in the application. The pages can then be unpinned by echoing any value into the /proc/xpmem/*pid* file, for example:

echo 1 > /proc/xpmem/5562

The echo command will not return until that process's pages are unpinned.

When the MPI application is resumed, the XPMEM kernel module will prevent these pages from paging as they are referenced by the application.

Chapter 8

MPI Performance Profiling

This chapter describes the perfcatch utility used to profile the performance of an MPI program. It covers the following topics:

- "Overview of perfcatch Utility" on page 51
- "Using the perfcatch Utility" on page 51
- "MPI_PROFILING_STATS Results File Example" on page 52
- "MPI Performance Profiling Environment Variables" on page 55
- "MPI Supported Profiled Functions"

For information on additional profiling tools, see "Using Profiling Tools with MPI Applications" on page 31.

Overview of perfcatch Utility

The perfcatch utility runs an MPI program with a wrapper profiling library that prints MPI call profiling information to a summary file upon MPI program completion. This MPI profiling result file is called MPI_PROFILING_STATS, by default (see "MPI_PROFILING_STATS Results File Example" on page 52). It is created in the current working directory of the MPI process with rank 0.

Using the perfcatch Utility

The syntax of the perfcatch utility is, as follows:

perfcatch [-v | -vofed | -i] cmd args

The perfcatch utility accepts the following options:

No option	Supports MPT
-v	Supports Voltaire MPI
-vofed	Supports Voltaire OFED MPI

Supports Intel MPI

To use perfcatch with an SGI Message Passing Toolkit MPI program, insert the perfcatch command in front of the executable name. Here are some examples:

mpirun -np 64 perfcatch a.out arg1
and

mpirun host1 32, host2 64 perfcatch a.out arg1

To use perfcatch with Intel MPI, add the -i options. An example is, as follows:

mpiexec -np 64 perfcatch -i a.out arg1

For more information, see the perfcatch(1) man page.

MPI_PROFILING_STATS Results File Example

-i

The MPI profiling result file has a summary statistics section followed by a rank-by-rank profiling information section. The summary statistics section reports some overall statistics, including the percent time each rank spent in MPI functions, and the MPI process that spent the least and the most time in MPI functions. Similar reports are made about system time usage.

The rank-by-rank profiling information section lists every profiled MPI function called by a particular MPI process. The number of calls and the total time consumed by these calls is reported. Some functions report additional information such as average data counts and communication peer lists.

An example MPI_PROFILING_STATS results file is, as follows:

_____ PERFCATCHER version 22 (C) Copyright SGI. This library may only be used on SGI hardware platforms. See LICENSE file for details. _____ MPI program profiling information Job profile recorded Wed Jan 17 13:05:24 2007 Program command line: /home/estes01/michel/sastest/mpi_hello_linux Total MPI processes 2 0.0054768 sec Total MPI job time, avg per rank Profiled job time, avg per rank 0.0054768 sec Percent job time profiled, avg per rank 100% 0.001 sec Total user time, avg per rank Percent user time, avg per rank 18.2588% Total system time, avg per rank 0.0045 sec 82.1648% Percent system time, avg per rank 5.75004e-07 sec Time in all profiled MPI routines, avg per rank Percent time in profiled MPI routines, avg per rank 0.0104989% Rank-by-Rank Summary Statistics _____ Rank-by-Rank: Percent in Profiled MPI routines Rank:Percent 0:0.0112245% 1:0.00968502% Least: Rank 1 0.00968502% Most: Rank 0 0.0112245% Load Imbalance: 0.000771% Rank-by-Rank: User Time Rank:Percent 0:17.2683% 1:19.3699% Least: Rank 0 17.2683% Most: Rank 1 19.3699% Rank-by-Rank: System Time Rank:Percent

```
1:77.4796%
     0:86.3416%
 Least: Rank 1 77.4796%
Most: Rank 0 86.3416%
Notes
____
Wtime resolution is
                            5e-08 sec
Rank-by-Rank MPI Profiling Results
-----
Activity on process rank 0
        Single-copy checking was not enabled.
              calls: 1 time: 6.50005e-07 s 6.50005e-07 s/call
comm_rank
Activity on process rank 1
        Single-copy checking was not enabled.
              calls: 1 time: 5.00004e-07 s 5.00004e-07 s/call
comm_rank
-----
recv profile
         cnt/sec for all remote ranks
local
    ANY_SOURCE 0
                     1
rank
_____
recv wait for data profile
         cnt/sec for all remote ranks
        0
local
              1
rank
-----
recv wait for data profile
```

local rank	cnt/sec 0		1	remote		
send profile	cnt/sec		all			
src rank	0		1			
ssend profile						
src rank	cnt/sec 0	-	1			
ibsend profile						
src rank	cnt/sec 0	for	all 1	destina	ation	ranks

MPI Performance Profiling Environment Variables

The MPI performance profiling environment variables are, as follows:

Variable	Description
MPI_PROFILE_AT_INIT	Activates MPI profiling immediately, that is, at the start of MPI program execution.
MPI_PROFILING_STATS_FIL	E Specifies the file where MPI profiling results are written. If not

specified, the file
MPI_PROFILING_STATS is written.

MPI Supported Profiled Functions

The MPI supported profiled functions are, as follows:

Note: Some functions may not be implemented in all language as indicated below.

Languages	Function
C Fortran	mpi_allgather
C Fortran	mpi_allgatherv
C Fortran	mpi_allreduce
C Fortran	mpi_alltoall
C Fortran	mpi_alltoallv
C Fortran	mpi_alltoallw
C Fortran	mpi_barrier
C Fortran	mpi_bcast
C Fortran	mpi_comm_create
C Fortran	mpi_comm_free
C Fortran	mpi_comm_group
C Fortran	mpi_comm_rank
C Fortran	mpi_finalize
C Fortran	mpi_gather
C Fortran	mpi_gatherv
С	mpi_get_count
C Fortran	<pre>mpi_group_difference</pre>
C Fortran	mpi_group_excl
C Fortran	mpi_group_free
C Fortran	mpi_group_incl
C Fortran	<pre>mpi_group_intersection</pre>

C Fortran	mpi_group_range_excl
C Fortran	mpi_group_range_incl
C Fortran	mpi_group_union
С	mpi_ibsend
C Fortran	mpi_init
С	mpi_init_thread
C Fortran	mpi_irecv
C Fortran	mpi_isend
С	mpi_probe
C Fortran	mpi_recv
C Fortran	mpi_reduce
C Fortran	mpi_scatter
C Fortran	mpi_scatterv
C Fortran	mpi_send
C Fortran	mpi_sendrecv
C Fortran	mpi_ssend
C Fortran	mpi_test
C Fortran	mpi_testany
C Fortran	mpi_wait
C Fortran	mpi_wait

Troubleshooting and Frequently Asked Questions

This chapter provides answers to some common problems users encounter when starting to use SGI MPI, as well as answers to other frequently asked questions. It covers the following topics:

- "What are some things I can try to figure out why mpirun is failing? " on page 59
- "My code runs correctly until it reaches MPI_Finalize() and then it hangs." on page 61
- "I keep getting error messages about MPI_REQUEST_MAX being too small." on page 61
- "I am not seeing stdout and/or stderr output from my MPI application." on page 62
- "How can I get the MPT software to install on my machine?" on page 62
- "Where can I find more information about the SHMEM programming model? " on page 62
- "The ps(1) command says my memory use (SIZE) is higher than expected. " on page 62
- "What does MPI: could not run executable mean?" on page 62
- "How do I combine MPI with insert favorite tool here?" on page 63
- "Why do I see "stack traceback" information when my MPI job aborts?" on page 64

What are some things I can try to figure out why mpirun is failing?

Here are some things to investigate:

- Look in /var/log/messages for any suspicious errors or warnings. For example, if your application tries to pull in a library that it cannot find, a message should appear here. Only the root user can view this file.
- Be sure that you did not misspell the name of your application.

• To find dynamic link errors, try to run your program without mpirun. You will get the "mpirun must be used to launch all MPI applications" message, along with any dynamic link errors that might not be displayed when the program is started with mpirun.

As a last resort, setting the environment variable LD_DEBUG to all will display a set of messages for each symbol that rld resolves. This produces a lot of output, but should help you find the cause of the link arror.

- Be sure that you are setting your remote directory properly. By default, mpirun attempts to place your processes on all machines into the directory that has the same name as \$PWD. This should be the common case, but sometimes different functionality is required. For more information, see the section on \$MPI_DIR and/or the -dir option in the mpirun man page.
- If you are using a relative pathname for your application, be sure that it appears in \$PATH. In particular, mpirun will not look in '.' for your application unless '.' appears in \$PATH.
- Run /usr/sbin/ascheck to verify that your array is configured correctly.
- Use the mpirun -verbose option to verify that you are running the version of MPI that you think you are running.
- Be very careful when setting MPI environment variables from within your .cshrc or .login files, because these will override any settings that you might later set from within your shell (due to the fact that MPI creates the equivalent of a fresh login session for every job). The safe way to set things up is to test for the existence of \$MPI_ENVIRONMENT in your scripts and set the other MPI environment variables only if it is undefined.
- If you are running under a Kerberos environment, you may experience unpredictable results because currently, mpirun is unable to pass tokens. For example, in some cases, if you use telnet to connect to a host and then try to run mpirun on that host, it fails. But if you instead use rsh to connect to the host, mpirun succeeds. (This might be because telnet is kerberized but rsh is not.) At any rate, if you are running under such conditions, you will definitely want to talk to the local administrators about the proper way to launch MPI jobs.
- Look in /tmp/.arraysvcs on all machines you are using. In some cases, you might find an errlog file that may be helpful.

- You can increase the verbosity of the Array Services daemon (arrayd) using the -v option to generate more debugging information. For more information, see the arrayd(8) man page.
- Check error messages in /var/run/arraysvcs.

My code runs correctly until it reaches MPI_Finalize() and then it hangs.

This is almost always caused by send or recv requests that are either unmatched or not completed. An unmatched request is any blocking send for which a corresponding recv is never posted. An incomplete request is any nonblocking send or recv request that was never freed by a call to MPI_Test(), MPI_Wait(), or MPI_Request_free().

Common examples are applications that call MPI_Isend() and then use internal means to determine when it is safe to reuse the send buffer. These applications never call MPI_Wait(). You can fix such codes easily by inserting a call to MPI_Request_free() immediately after all such isend operations, or by adding a call to MPI_Wait() at a later place in the code, prior to the point at which the send buffer must be reused.

I keep getting error messages about MPI_REQUEST_MAX being too small.

There are two types of cases in which the MPI library reports an error concerning MPI_REQUEST_MAX. The error reported by the MPI library distinguishes these.

MPI has run out of unexpected request entries; the current allocation level is: XXXXXX

The program is sending so many unexpected large messages (greater than 64 bytes) to a process that internal limits in the MPI library have been exceeded. The options here are to increase the number of allowable requests via the MPI_REQUEST_MAX shell variable, or to modify the application.

MPI has run out of request entries; the current allocation level is: MPI_REQUEST_MAX = XXXXX

You might have an application problem. You almost certainly are calling MPI_Isend() or MPI_Irecv() and not completing or freeing your request objects. You need to use MPI_Request_free(), as described in the previous section.

I am not seeing stdout and/or stderr output from my MPI application.

All stdout and stderr is line-buffered, which means that mpirun does not print any partial lines of output. This sometimes causes problems for codes that prompt the user for input parameters but do not end their prompts with a newline character. The only solution for this is to append a newline character to each prompt.

You can set the MPI_UNBUFFERED_STDIO environment variable to disable line-buffering. For more information, see the MPI(1) and mpirun(1) man pages.

How can I get the MPT software to install on my machine?

MPT RPMs are included in ProPack releases. In addition, you can obtain MPT RPMs from the SGI Support website at

http://support.sgi.com
under "Downloads".

Where can I find more information about the SHMEM programming model?

See the intro_shmem(3) man page.

The ps(1) command says my memory use (SIZE) is higher than expected.

At MPI job start-up, MPI calls the SHMEM library to cross-map all user static memory on all MPI processes to provide optimization opportunities. The result is large virtual memory usage. The ps(1) command's SIZE statistic is telling you the amount of virtual address space being used, not the amount of memory being consumed. Even if all of the pages that you could reference were faulted in, most of the virtual address regions point to multiply-mapped (shared) data regions, and even in that case, actual per-process memory usage would be far lower than that indicated by SIZE.

What does MPI: could not run executable mean?

This message means that something happened while mpirun was trying to launch your application, which caused it to fail before all of the MPI processes were able to handshake with it.

The mpirun command directs arrayd to launch a master process on each host and listens on a socket for those masters to connect back to it. Since the masters are children of arrayd, arrayd traps SIGCHLD and passes that signal back to mpirun whenever one of the masters terminates. If mpirun receives a signal before it has established connections with every host in the job, it knows that something has gone wrong.

How do I combine MPI with *insert favorite tool here*?

In general, the rule to follow is to run mpirun on your tool and then the tool on your application. Do not try to run the tool on mpirun. Also, because of the way that mpirun sets up stdio, seeing the output from your tool might require a bit of effort. The most ideal case is when the tool directly supports an option to redirect its output to a file. In general, this is the recommended way to mix tools with mpirun. Of course, not all tools (for example, dplace) support such an option. However, it is usually possible to make it work by wrapping a shell script around the tool and having the script do the redirection, as in the following example:

```
> cat myscript
     #!/bin/sh
     setenv MPI_DSM_OFF
     dplace -verbose a.out 2> outfile
     > mpirun -np 4 myscript
    hello world from process 0
    hello world from process 1
    hello world from process 2
    hello world from process 3
     > cat outfile
     there are now 1 threads
     Setting up policies and initial thread.
     Migration is off.
     Data placement policy is PlacementDefault.
     Creating data PM.
     Data pagesize is 16k.
     Setting data PM.
     Creating stack PM.
     Stack pagesize is 16k.
     Stack placement policy is PlacementDefault.
     Setting stack PM.
     there are now 2 threads
```

there are now 3 threads there are now 4 threads there are now 5 threads

Why do I see "stack traceback" information when my MPI job aborts?

More information can be found in the MPI(1) man page in descriptions of the MPI_COREDUMP and MPI_COREDUMP_DEBUGGER environment variables.

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